



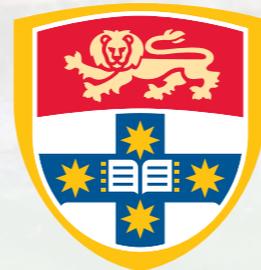
*59th Annual Meeting of
the Australian Mathematical Society*

Flinders University, Adelaide, 28 Sep.-1 Oct. 2015

A simplified approach to the regularising effect of nonlinear semigroups

A joint work with Prof Thierry Coulhon (PSL/ANU)

Daniel Hauer



**THE UNIVERSITY OF
SYDNEY**

RECENT TRENDS IN NONLINEAR EVOLUTION EQUATIONS WORKSHOP

4TH & 5TH NOVEMBER 2015

LECTURE ROOM 5

PHYSICS BUILDING

UNIVERSITY OF SYDNEY

[HTTP://WWW.MATHS.USYD.EDU.AU/U/DHAUER/NONLINEAR-EVOLUTION/](http://www.maths.usyd.edu.au/u/dhauer/nonlinear-evolution/)

SPEAKERS:

- BEN ANDREWS (ANU)
- JULIE CLUTTERBUCK (MONASH)
- JAMES MCCOY (UOW)
- EN DANGER (USYD)
- DANIEL DANERS (USYD)
- DAREK ROBINSON (ANU)
- JÉRÔME DRONIOU (MONASH)
- YIHONG DU (UNE)
- DAVID GALLOWAY (USYD)
- PIERRE PORTAL (ANU)
- NEIL TRUDINGER (ANU)
- FERNANDO QUIRÓS (SPAIN)
- XU-JIA WANG (ANU)
- GLEN WHEELER (UOW)

ORGANISERS:

- DANIEL HAUER (USYD)
- VALENTINA-MIRA WHEELER (UOW)



Digital Print Solutions



THE UNIVERSITY OF
SYDNEY

The framework of his talk



The framework of this talk

Let (Σ, μ) be a σ -finite measure space,



The framework of this talk

Let (Σ, μ) be a σ -finite measure space,

$X = L^q(\Sigma, \mu)$ for some $1 \leq q \leq \infty$,



The framework of this talk

Let (Σ, μ) be a σ -finite measure space,

$X = L^q(\Sigma, \mu)$ for some $1 \leq q \leq \infty$,

A an operator on X with domain $D(A)$.



The framework of this talk

Let (Σ, μ) be a σ -finite measure space,

$X = L^q(\Sigma, \mu)$ for some $1 \leq q \leq \infty$,

A an operator on X with domain $D(A)$.

For given $u_0 \in X$ let $u: [0, \infty) \rightarrow X$ be a solution of
(in some sense)

$$(EP) \begin{cases} \frac{du(t)}{dt} + Au(t) \ni 0 & \text{for } t > 0, \\ u(0) = u_0. \end{cases}$$



The framework of this talk

Suppose A is m -accretive in X , that is,



The framework of this talk

Suppose A is m -accretive in X , that is,

(Accretive) for every $\lambda > 0$ the resolvent oper. $J_\lambda := (1 + \lambda A)^{-1}$ is X -contractive,

$$\|J_\lambda u - J_\lambda \hat{u}\|_X \leq \|u - \hat{u}\|_X \quad \forall u, \hat{u} \in \text{Rg}(1 + \lambda A)$$

(Rg-cond.) this is (for all) $\lambda > 0$, $\text{Rg}(1 + \lambda A) = X$.



The framework of this talk

Suppose A is m -accretive in X , that is,

(Accretive) for every $\lambda > 0$ the resolvent oper. $J_\lambda := (1 + \lambda A)^{-1}$ is X -contractive,

$$\|J_\lambda u - J_\lambda \hat{u}\|_X \leq \|u - \hat{u}\|_X \quad \forall u, \hat{u} \in \text{Rg}(1 + \lambda A)$$

(Rg-cond.) this is (for all) $\lambda > 0$, $\text{Rg}(1 + \lambda A) = X$.

Then by Crandall-Liggett '71,

$$(GP) \begin{cases} \frac{du}{dt}(t) + Au(t) \ni 0 & \text{for } t > 0, \\ u(0) = u_0 \in \overline{D(A)} \end{cases}$$

is well-posed in the sense of mild solutions.



The framework of this talk

Now, for given $u_0 \in X$ a function $u \in \mathcal{C}([0, \infty); X)$ is called a **mild solution** of (EP) if for every $T > 0$, $\varepsilon > 0$ and partition $0 = t_0 < t_1 < \dots < t_N = T$ of $[0, T]$ s.t. $t_i - t_{i-1} < \varepsilon$

there is a piecewise constant function $u_{\varepsilon, N}^{(t)} := \sum_{i=1}^N u_{\varepsilon, N} \mathbb{1}_{(t_{i-1}, t_i]}$ where $u_{\varepsilon, N}$ on $(t_{i-1}, t_i]$ solves "recursively"

the finite difference equation $u_{\varepsilon, N} + (t_i - t_{i-1}) A u_{\varepsilon, N} = u_{\varepsilon, N-1}$

such that $\sup_{t \in [0, T]} \|u_{\varepsilon, N}^{(t)} - u(t)\|_X \leq \varepsilon$.



The framework of this talk

By the celebrated Crandall-Liggett Theorem (1971),
if A is m -accretive in X , then for every $u_0 \in \overline{D(A)}$
there is a unique mild solution of (EP) and the
solution is given by the exponential formula

$$u(t) := \lim_{h \rightarrow 0} \left(1 + \frac{t}{h} A \right)^{-h} u_0 \quad \text{unif. on comp. subintervals of } (0, \infty).$$



The framework of this talk

For given $u_0 \in X$, we call a function $u \in \mathcal{C}([0, \infty); X)$
a **strong solution** of (EP) if $u \in W_{loc}^{1,1}([0, \infty); X)$,
 $u(0) = u_0$ in X and for a.e. $t > 0$ one has
 $u(t) \in D(A)$ & $-\frac{du(t)}{dt} \in Au(t)$.



The framework of this talk

For given $u_0 \in \overline{D(A)}$, let $u: [0, \infty) \rightarrow X$ be the
the mild solution of (EP), then set

$$\overline{I}_t u_0 := u(t) \quad \forall t \geq 0.$$



The framework of this talk

For given $u_0 \in \overline{D(A)}$, let $u: [0, \infty) \rightarrow X$ be the mild solution of (EP), then set

$$\overline{T}_t u_0 := u(t) \quad \forall t \geq 0.$$

Then the family $\{\overline{T}_t\}_{t \geq 0}$ of mappings $\overline{T}_t: \overline{D(A)} \rightarrow \overline{D(A)}$ satisfies:

- ▷ $\overline{T}_t \circ \overline{T}_s = \overline{T}_{t+s} \quad \forall t, s \geq 0$ (semi-group)
- ▷ $\lim_{t \rightarrow 0^+} \|\overline{T}_t u - u\|_X = 0 \quad \forall u \in \overline{D(A)}$ (Strong Cont.)
- ▷ $\|\overline{T}_t u - \overline{T}_t \hat{u}\|_X \leq \|u - \hat{u}\|_X \quad \forall u, \hat{u} \in \overline{D(A)}$ (X-contractive)



The framework of this talk

The abstract framework

$$(EP) \begin{cases} \frac{du(t)}{dt} + Au(t) \ni 0 & \text{for } t > 0, \\ u(0) = u_0 \in \overline{D(A)} \end{cases}$$

allows to establish existence, uniqueness & cont. dependence on u_0 of many important parabolic bdy-value problems:



The framework of this talk

The abstract framework

$$(EP) \begin{cases} \frac{du}{dt}(t) + Au(t) \ni 0 & \text{for } t > 0, \\ u(0) = u_0 \in \overline{D(A)} \end{cases}$$

allows to establish existence, uniqueness & cont. dependence on u_0 of many important parabolic bdy-value problems:

$$\triangleright X = L^2(\Omega) : \quad A = -\operatorname{div}(a(x) \nabla u) \\ \Omega \subseteq \mathbb{R}^d \text{ domain} \quad \text{or} \quad A = -\operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right)$$



The framework of this talk

The abstract framework

$$(EP) \begin{cases} \frac{du}{dt}(t) + Au(t) \ni 0 & \text{for } t > 0, \\ u(0) = u_0 \in \overline{D(A)} \end{cases}$$

allows to establish existence, uniqueness & cont. dependence on u_0 of many important parabolic bdy-value problems:

$$\triangleright X = L^1(\Omega) : \quad A = -\Delta_p u^m, \quad u^m := |u|^{m-1} u, \quad m > 1$$





THE UNIVERSITY OF
SYDNEY

Daniel Hauer

Main subject of this talk



Main subject of this talk

To investigate the "regularising effect":

For given $u \in L^q(\Sigma, \mu)$ for some $q \geq 1$,

$T_t u \in L^r(\Sigma, \mu) \quad \forall t > 0$ & some $q < r \leq \infty$
+ uniform bdds/decay rates as $t \rightarrow \infty$.



Outline of this talk

- ① Log-Sobolev is not always the direct & simplest way
- ② Other results to this subject
- ③ Our motivation / AIM
- ④ Main theorems
- ⑤ Applications



① Log-Sobolev is not always the direct
& simplest way



① Log-Sobolev is not always the direct & simplest way

The approach:

1. By using a *known* Sobolev inequality, one derives a Log-Sobolev inequality.



① Log-Sobolev is not always the direct & simplest way

The approach:

1. By using a *known* Sobolev inequality, one derives a Log-Sobolev inequality.
2. When $\tau: [0, \infty) \rightarrow [p, \infty)$ is non-decreasing & C^1 , then one shows by using the Log-Sobolev inequality that
$$s \mapsto y(s) := \log \|u(s)\|_{L^{\tau(s)}}^2$$
 satisfies a differential inequality.



① Log-Sobolev is not always the direct & simplest way

The approach:

1. By using a *known* Sobolev inequality, one derives a Log-Sobolev inequality.
2. When $\tau: [0, \infty) \rightarrow [p, \infty)$ is non-decreasing & C^1 , then one shows by using the Log-Sobolev inequality that

$s \mapsto y(s) := \log \|u(s)\|_{L^{\tau(s)}}$
satisfies a differential inequality.

$\Rightarrow L^q \rightarrow L^{\infty}$ -regularising effect of $u(0) \mapsto u(t), t > 0$.



② Other results to this subject



② Other results to this subject

▷ Benilan '1978 (Truncation & Moser-iter.)



② Other results to this subject

- ▷ Bénéilan '1978 (Truncation & Moser-iter.)
- ▷ Véron '1979 (^{more general} Moser simplified)



② Other results to this subject

- ▷ Bénéilan '1978 (Truncation & Moser-iter.)
- ▷ Véron '1979 (Moser ^{more general} simplified)
- ▷ Porzio '2009 (for Leray-Lions)



② Other results to this subject

▷ Bénéilan '1978 (Truncation & Moser-iter.)

▷ Véron '1979 (Moser ^{more general} simplified)

▷ Porzio '2009 (for Leray-Lions)

▷

▷

▷

Many others but for more specific situations.



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev appr.):



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev aprt.):

$$q \geq p$$
$$\langle -\Delta_p u, |u|^{q-p} u \rangle = (q-p+1) \int_{\Omega} |\nabla u|^p |u|^{q-p} dx$$



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev appr.):

$$\begin{aligned} q \geq p \\ \langle -\Delta_p u, |u|^{q-p} u \rangle &= (q-p+1) \int_{\Omega} |\nabla u|^p |u|^{q-p} dx \\ &= (q-p+1) \int_{\Omega} |\nabla u \cdot |u|^{\frac{q-p}{p}}|^p dx \end{aligned}$$



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev appr.):

$$\begin{aligned} q \geq p \\ \langle -\Delta_p u, |u|^{q-p} u \rangle &= (q-p+1) \int_{\Omega} |\nabla u|^p |u|^{q-p} dx \\ &= (q-p+1) \int_{\Omega} |\nabla u \cdot |u|^{\frac{q-p}{p}}|^p dx \\ &= \frac{(q-p+1)}{\left(\frac{q-p}{p}+1\right)^p} \int_{\Omega} |\nabla (|u|^{\frac{q-p}{p}} u)|^p dx \end{aligned}$$



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev appr.):

$$\begin{aligned} q \geq p \\ \langle -\Delta_p u, |u|^{q-p} u \rangle &= (q-p+1) \int_{\Omega} |\nabla u|^p |u|^{q-p} dx \\ &= (q-p+1) \int_{\Omega} |\nabla u \cdot |u|^{\frac{q-p}{p}}|^p dx \\ &= \frac{(q-p+1)}{\left(\frac{q-p}{p}+1\right)^p} \int_{\Omega} |\nabla (|u|^{\frac{q-p}{p}} u)|^p dx \\ &\geq C_{q,p} \left(\int_{\Omega} | |u|^{\frac{q-p}{p}} u |^{p^*} dx \right)^{\frac{p}{p^*}} \end{aligned}$$



② Other results to this subject

Main tool in all these approaches
(including log-Sobolev appr.):

One builds a "one parameter family" of
(log-) Sobolev inequalities.





③ Our motivation / AIM

To develop a unified machinery,



③ Our motivation / AIM

To develop a unified machinery,
Which avoids :

▷ the construction of one-parameter families of (log-) Sobolev ineq.



③ Our motivation / AIM

To develop a unified machinery,
Which avoids :

- ▷ the construction of one-parameter families of (log-) Sobolev ineq.
- ▷ too much regularity.



③ Our motivation / AIM

To develop a unified machinery,
which concerns

▷ completely accretive operators A ,
i.e., $\forall \lambda > 0$ the resolvent J_λ is L^q -contractive
+ order preserving $\forall 1 \leq q \leq \infty$



③ Our motivation / AIM

To develop a unified machinery,
which concerns

▷ completely accretive operators A ,
i.e., $\forall \lambda > 0$ the resolvent J_λ is L^q -contractive
+ order preserving $\forall 1 \leq q \leq \infty$

▷ accretive operators A
non-increasing resolvent J_λ in L^q
(i.e. $\|J_\lambda\|_q \leq \|u\|_q$) $\forall 1 \leq q \leq \infty$



④ Main theorems

1 Theorem [Coulhon, H. '15] Sobolev $\Rightarrow L^2$ - L^r -reg

Let A be m -completely accretive in $L^2(\Sigma, \mu)$ with dense domain & $0 \in A_0$.

If there are $2 \leq r \leq \infty$, $\delta > 0$ & $C > 0$ s.t.

(Sob) $\|u - \hat{u}\|_{\tau}^{\delta} \leq C \langle u - \hat{u}, v - \hat{v} \rangle_2$
for all $(u, v), (u, \hat{u}) \in A$, then $\{T_t\}_{t \geq 0} \sim -A$ satisfies

$$\|T_t u - T_t \hat{u}\|_{\tau} \leq \left(\frac{C}{2}\right)^{\frac{1}{\delta}} t^{-\frac{1}{\delta}} \|u - \hat{u}\|_2^{\frac{2}{\delta}} \quad \forall u, \hat{u} \in L^2.$$



④ Main theorems

* Theorem [Eouphon, H. '15] Sobolev $\Rightarrow L^2$ - L^r -reg

Let A be m -accretive in $L^1(\Sigma, \mu)$ with non-increasing resolvent in all L^q & dense domain.

If there are $2 \leq r \leq \infty$, $\delta > 0$ & $C > 0$ s.t.

(Sob) $\|u\|_r^\delta \leq C \langle u, v \rangle_2$
for all $(u, v) \in A_n(L^2 \times L^2)$, then $\{T_t\}_{t \geq 0} \sim -A$ satisfies

$$\|T_t u\|_r \leq \left(\frac{C}{2}\right)^{\frac{1}{\delta}} t^{-\frac{1}{\delta}} \|u\|_2^{\frac{2}{\delta}} \quad \forall u \in L^2.$$



④ Main theorems

2 Theorem [Eouphon, H.'15] Sobolev $\Rightarrow L^q$ - L^∞ -reg.

Let A be m -completely accretive in $L^2(\Sigma, \mu)$ with dense domain & $0 \in A_0$.

If there are $2 < \tau < \infty$, $\beta > 0$ & $c > 0$ s.t.h. $\frac{\tau}{\beta} > 1$ &

(Sob) $\|u - \hat{u}\|_\tau^\beta \leq c \cdot \langle u - \hat{u}, v - \hat{v} \rangle_2$
 for all $(u, v), (u, \hat{u}), (v, \hat{v}) \in A$, then $\{T_t\}_{t \geq 0} \sim -A$ satisfies

$$\|T_t u - T_t \hat{u}\|_\infty \lesssim t^{-\delta} \|u - \hat{u}\|_{\frac{\tau}{\beta} w_0}^\delta \quad \forall u, \hat{u} \in L^{\frac{\tau}{\beta} w_0},$$

for any $w_0 > \beta$ satisfying $(\frac{\tau}{\beta} - 1)w_0 + \beta - 2 > 0$
 with

$$\delta = \frac{1}{(\frac{\tau}{\beta} - 1)w_0 + \beta - 2} \quad \gamma = \frac{(\frac{\tau}{\beta} - 1)w_0}{(\frac{\tau}{\beta} - 1)w_0 + \beta - 2}.$$

④ Main theorems

3 Theorem [Eouphon, H.'15] Extrapolation towards L^1

For $1 \leq q < r \leq \infty$. let $\{T_t\}_{t \geq 0}$ be L^1 -contractive semigroup on $L^1 \cap L^r(\Sigma, \mu)$, $T_t u \equiv 0$ & suppose,

there are $\delta, \gamma > 0$ s.t.

$$\|T_t u - T_t \hat{u}\|_r \leq C t^{-\delta} \|u - \hat{u}\|_q^\gamma \quad \forall t > 0 \text{ \& } \forall u, \hat{u} \in L^1 \cap L^r$$

For $\Theta_r := \frac{r-q}{q(r-1)} > 0$ if $r < \infty$ & $\Theta_\infty := \frac{1}{q}$ if $r = \infty$

assume that $\gamma(1 - \Theta_r) < 1$.

Then $\|T_t u - T_t \hat{u}\|_r \leq (2^\delta C)^{\frac{1}{\Theta}} t^{-\frac{\delta}{\Theta}} \|u - \hat{u}\|_q^{\frac{\gamma}{\Theta}}$
with $\Theta := 1 - \gamma(1 - \Theta)$. $\forall u, \hat{u} \in L^1(\Sigma, \mu)$



⑤ Applications



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$A := \left\{ (u, v) \in L^2(\mathbb{R}^d) \times L^2(\mathbb{R}^d) \mid \begin{array}{l} u \in BV(\mathbb{R}^d) \text{ \& } \exists z \in L^\infty(\mathbb{R}^d, \mathbb{R}^d), \|z\|_\infty \leq 1, \\ v = -\operatorname{div} z \, \mathcal{H}^d \text{ \& } (z, Du) = |Du| \end{array} \right\}$$



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$A := \left\{ (u, v) \in L^2(\mathbb{R}^d) \times L^2(\mathbb{R}^d) \mid \begin{array}{l} u \in BV(\mathbb{R}^d) \text{ \& } \exists z \in L^\infty(\mathbb{R}^d, \mathbb{R}^d), \|z\|_\infty \leq 1, \\ v = -\operatorname{div} z \text{ in } \mathcal{D}' \text{ \& } (z, Du) = |Du| \end{array} \right\}$$

is the total variation flow operator $-\operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right) = \Delta_1$
in $L^2(\mathbb{R}^d)$. (1-Laplace op.)



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$A := \left\{ (u, v) \in L^2(\mathbb{R}^d) \times L^2(\mathbb{R}^d) \mid \begin{array}{l} u \in BV(\mathbb{R}^d) \text{ \& } \exists z \in L^\infty(\mathbb{R}^d, \mathbb{R}^d), \|z\|_\infty \leq 1 \\ v = -\operatorname{div} z \text{ in } \mathcal{D}' \text{ \& } (z, Du) = |Du| \end{array} \right\}$$

is the total variation flow operator $-\operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right) = \Delta_1$
in $L^2(\mathbb{R}^d)$. (1-Laplace op.)

$\Rightarrow A$ is m -completely accretive in $L^2(\mathbb{R}^d)$ & $0 \in A_0$.



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$A := \left\{ (u, v) \in L^2(\mathbb{R}^d) \times L^2(\mathbb{R}^d) \mid \begin{array}{l} u \in BV(\mathbb{R}^d) \text{ \& } \exists z \in L^\infty(\mathbb{R}^d, \mathbb{R}^d), \|z\|_\infty \leq 1 \\ v = -\operatorname{div} z \text{ in } \mathcal{D}' \text{ \& } (z, Du) = |Du| \end{array} \right\}$$

is the total variation flow operator $-\operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right) = \Delta_1$
in $L^2(\mathbb{R}^d)$. (1-Laplace op.)

$\Rightarrow A$ is m -completely accretive in $L^2(\mathbb{R}^d)$ & $0 \in A_0$.

Sobolev is

$$\|u\|_{L^{d/(d-1)}} \leq C |Du|(\mathbb{R}^d)$$



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$\Rightarrow \forall (u, v) \in A, \quad \langle u, v \rangle_2 = \int_{\mathbb{R}^d} -\operatorname{div}(z) \cdot u \, dx$$



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$\Rightarrow \forall (u, v) \in A, \quad \langle u, v \rangle_2 = \int_{\mathbb{R}^d} -\operatorname{div}(z) \cdot u \, dx$$

Green's formula (Anzellotti) $\stackrel{z}{=} \int_{\mathbb{R}^d} (z, Du)$



⑤ Applications

1. Total variational flow in \mathbb{R}^d

Thm 1*

$$\implies \|\tau_t^u\|_{\frac{d}{d-1}} \leq \frac{C}{2} t^{-1} \|u\|_2^2 \quad \forall t > 0$$

$\& \forall u \in L^2(\mathbb{R}^d)$



⑤ Applications

1. Total variational flow in \mathbb{R}^d

$$\begin{aligned} \text{Thm 1}^* \\ \implies \end{aligned} \quad \|T_t u\|_{\frac{d}{d-1}} \leq \frac{C}{2} t^{-1} \|u\|_2^2 \quad \forall t > 0 \\ \& \quad \forall u \in L^2(\mathbb{R}^d)$$

Since $\frac{d}{d-1} > 1$,

$$\begin{aligned} \text{Thm 2}^* \\ \implies \end{aligned} \quad \|T_t u\|_{\infty} \lesssim t^{-\frac{1}{(d/(d-1)-1)m_0-1}} \|u\|_{\frac{dm_0}{d-1}} \quad \forall u \in L^{\frac{dm_0}{d-1}}$$

for any $m_0 > 1$ s.t.
 $(\frac{d}{d-1}-1)m_0-1 > 0$



Thank You!



RECENT TRENDS IN NONLINEAR EVOLUTION EQUATIONS WORKSHOP

4TH & 5TH NOVEMBER 2015

LECTURE ROOM 5

PHYSICS BUILDING

UNIVERSITY OF SYDNEY

[HTTP://WWW.MATHS.USYD.EDU.AU/U/DHAUER/NONLINEAR-EVOLUTION/](http://www.maths.usyd.edu.au/u/dhauer/nonlinear-evolution/)

SPEAKERS:

- BEN ANDREWS (ANU)
- JULIE CLUTTERBUCK (MONASH)
- JAMES MCCOY (UOW)
- EN DANGER (USYD)
- DANIEL DANERS (USYD)
- DAREK ROBINSON (ANU)
- JÉRÔME DRONIOU (MONASH)
- YIHONG DU (UNE)
- DAVID GALLOWAY (USYD)
- PIERRE PORTAL (ANU)
- NEIL TRUDINGER (ANU)
- FERNANDO QUIRÓS (SPAIN)
- XU-JIA WANG (ANU)
- GLEN WHEELER (UOW)

ORGANISERS:

- DANIEL HAUER (USYD)
- VALENTINA-MIRA WHEELER (UOW)

