# The vanishing discount problem for systems of Hamilton-Jacobi equations

Hitoshi Ishii

Tsuda University (Waseda University)

Asia-Pacific Analysis and PDE seminar. May 18, 2020

Vanishing discount problem

Convex, coercive HJ equations

Ergodic problem

An approach to Theorem 3

Systems of HJ equations

Appendix

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

# VANISHING DISCOUNT PROBLEM

Scalar Case: We consider the Hamilton-Jacobi equation

$$(\mathsf{P}_{\lambda})$$
  $\lambda v(x) + H(x, Dv(x)) = 0$  in  $\mathbb{T}^n$ .

Here

$$\left(egin{array}{c} v=v^\lambda & ext{the unknown function on }\mathbb{T}^n,\ Dv=(v_{x_1},...,v_{x_n}),\ \lambda>0 & ext{a given constant, discount factor,}\ H & ext{a given function of }(x,p)=(x,Dv(x)). \end{array}
ight.$$

**Problem:** asymptotic behavior of  $v^{\lambda}$  as  $\lambda \to 0$ .

p.1

CONVEX, COERCIVE HJ EQUATIONS Hypotheses:

(H0) Continuity:  $H \in C(\mathbb{T}^n \times \mathbb{R}^n)$ .

(H1)  $\boldsymbol{H}$  is convex,

 $p\mapsto H(x,p)$  is convex.

(H2)  $\boldsymbol{H}$  is coercive,

$$\lim_{|p| o \infty} \min_{x \in \mathbb{T}^n} H(x,p) = \infty.$$

Property of *H*:

$$H(x,p) \ge \delta |p| - C \quad (\exists \delta > 0, \exists C > 0).$$

Example:  $H(x,p) = |p|^m - f(x)$ ,  $m \ge 1$ ,  $f \in C(\mathbb{T}^n)$ .

p.2

Theorem 1 For each  $\lambda > 0$  problem (P<sub> $\lambda$ </sub>) has a unique solution  $v^{\lambda}$ . Furthermore,

 $(\lambda v^{\lambda})_{\lambda>0}$  is uniformly bounded,  $(v^{\lambda})_{\lambda>0}$  is equi-Lipschitz continuous.

• If  $C_0 \geq |H(x,0)|$ , then

 $\lambda(C_0/\lambda)+H(x,0)\geq 0, \qquad \lambda(-C_0/\lambda)+H(x,0)\leq 0,$ 

and, by comparison,  $-C_0/\lambda \leq v^\lambda(x) \leq C_0/\lambda.$ 

ullet Since  $H(x,p)\geq \delta |p|-C$ , we have

 $|\delta|Dv^{\lambda}(x)| \leq C + \lambda \|v^{\lambda}\|_{\infty}.$ 

Notation. Lagrangian of *H*:

$$L(x,\xi) := \sup_{p \in \mathbb{R}^n} [\xi \cdot p - H(x,p)].$$

Properties: *L* is convex and lower semicontinuous on  $\mathbb{T}^n \times \mathbb{R}^n$ .

$$egin{aligned} L(x,\xi) &\geq -H(x,0), \ L(x,\xi) &\geq A|\xi| - H(x,A\xi/|\xi|) \ &\geq A|\xi| - \max_{|p|\leq A} H(x,p) \ \ orall A > 0, \ L(x,\xi) &\leq \sup_p (|\xi||p| - \delta|p| + C) = C \quad orall \xi \in B_\delta. \end{aligned}$$

Recall here that  $H(x,p) \geq \delta |p| - C$ .

p.4

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ = 差 = のへで

#### ERGODIC PROBLEM

Formal expansion of the solution of  $(P_{\lambda})$ :

$$v^{\lambda}(x) pprox a_0(x)\lambda^{-1} + a_1(x) + a_2(x)\lambda + \cdots$$

Plug this into  $(P_{\lambda})$ :

$$a_0(x)+a_1(x)\lambda+a_2(x)\lambda^2+\cdots +H(x,Da_0(x)\lambda^{-1}+Da_1(x)+Da_2(x)\lambda+\cdots)pprox 0.$$

We deduce that

$$Da_0(x)=0$$
 i.e.  $a_0(x)\equiv a_0$  ( constant ),  $a_0+H(x,Da_1(x))=0.$ 

The ergodic problem or additive eigenvalue problem:

p.5

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

The problem of finding a constant  $c \in \mathbb{R}$  and a function  $u \in C(\mathbb{T}^n)$  satisfying

(E) 
$$H(x, Du(x)) = c$$
 in  $\mathbb{T}^n$ .

A classical result:

Theorem 2 (Lions-Papanicolaou-Varadhan, 1987) Under (H0), (H2), there exists a solution  $(c, u) \in \mathbb{R} \times C(\mathbb{T}^n)$ of (E). Moreover, the constant c is unique.

• The constant *c* is called the critical value, additive eigenvalue, or ergodic constant.

Their proof is to show that for some  $(c, u) \in \mathbb{R} \times C(\mathbb{T}^n)$ ,

$$egin{cases} -\lambda v^\lambda(x) &
ightarrow c & {
m uniformly on } \mathbb{T}^n, \ v^\lambda(x) + \lambda^{-1}c &
ightarrow u(x) & {
m uniformly on } \mathbb{T}^n \ & {
m along \ a \ subsequence }, \end{cases}$$

・ロト 4個ト 4 目 ト 4 目 ト p.6 の Q Q

 $\begin{array}{ll} \text{Main question:} & \text{does the whole family} \quad \{v^\lambda+\lambda^{-1}c\}_{\lambda>0}\\ \text{converges to a function as } \lambda\to 0+? \end{array}$ 

• The ergodic problem (E) has <u>multiple solutions</u>. If u is a solution of (E), then u + const is a solution. Consider the case

$$Du \cdot (Du - D\psi) = 0$$
 in  $\mathbb{T}^n$ , with  $\psi \in C^1(\mathbb{T}^n)$ .

We have many solutions:

$$u=C_1, \qquad u=\psi+C_2, \qquad u=\min\{C_1,\psi+C_2\}.$$

p.7

• Ergodic problem (E) arises in the <u>ergodic optimal control</u>, the <u>homogenization</u> of HJ equations, and the <u>large-time behavior</u> of solutions of evolutionary HJ equations.

A decisive result on the main question:

Theorem 3 (Davini-Fathi-Iturriaga-Zavidovique, 2016) Assume (H0)–(H2). Let c be the critical value. Then, for some function  $v^0 \in C(\mathbb{T}^n)$ , as  $\lambda \to 0+$ ,  $v^{\lambda}(x) + \lambda^{-1}c \to v^0(x)$  in  $C(\mathbb{T}^n)$ .

• If *H* is not convex, the convergence of the whole family does not hold in general. A counterexample by B. Ziliotto (2019).

p.8

Related work:

1) A. Davini, A. Fathi, R. Iturriaga, M. Zavidovique,

Coercive, convex HJ equation on  $\mathbb{T}^n$  (closed manifold).

2) E. S. Al-Aidarous, E. O. Alzahrani, HI, A. M. M. Younas,

Coercive, convex HJ equation on a bounded domain with the Neumann type BC.

3) H. Mitake, H. V. Tran

Viscous HJ equation on  $\mathbb{T}^n$ , with coercive and convex

Hamiltonian. (2nd-order degenerate elliptic PDEs.)

4) D. Gomes, H. Mitake, H. V. Tran

Coercive, quasi-convex HJ equation on  $\mathbb{T}^n$ .

5) HI, H. Mitake, H. V. Tran,

2nd-order fully nonlinear, convex, degenerate elliptic PDEs on  $\mathbb{T}^n$ 

or on a bounded domain with BC.

6) B. Ziliotto,

A counterexample, with non-convex Hamiltonian.

• Use of Mather measures.

#### An Approach to Theorem 3

We review the proof of Theorem 3 (Davini et al.).

 $\mathcal{P} = \mathcal{P}(\mathbb{T}^n \times \mathbb{R}^n)$  all Borel probability measures on  $\mathbb{T}^n \times \mathbb{R}^n$ .  $\mathcal{P}_1 = \mathcal{P}_1(\mathbb{T}^n \times \mathbb{R}^n)$  all  $\mu \in \mathcal{P}$  such that

$$\langle \mu, |\xi| 
angle := \int_{\mathbb{T}^n imes \mathbb{R}^n} |\xi| \, \mu(dxd\xi) < \infty.$$

(the function  $(x,\xi)\mapsto |\xi|$  is denoted by  $|\xi|)$ 

Fix 
$$(z,\lambda)\in\mathbb{T}^n imes [0,\,\infty).$$

 $\mathfrak{C}(z,\lambda)$  (closed measures) := { $\mu \in \mathcal{P}_1 \mid \lambda \psi(z) = \langle \mu, \xi \cdot D\psi + \lambda \psi \rangle \ \forall \psi \in C^1(\mathbb{T}^n)$ }.

Note that

$$\lambda u(x) + H(x, Du(x)) = \sup_{\xi} (\lambda u(x) + \xi \cdot Du(x) - L(x, \xi)).$$

When  $\lambda = 0$ , the defining condition reads

$$0 = \langle \mu, \xi \cdot D\psi 
angle \ \ orall \psi \in C^1(\mathbb{T}^n).$$

So, we write  $\mathfrak{C}(0)$  for  $\mathfrak{C}(z,0)$ .

Theorem 4 Assume (H0)–(H2). If 
$$\lambda > 0$$
, then  $\lambda v^{\lambda}(z) = \min_{\mu \in \mathfrak{C}(z,\lambda)} \langle \mu,L \rangle.$ 

• Any minimizer  $\mu$  of the optimization problem above is called a discounted Mather measure.  $\mathfrak{M}(z,\lambda) = \mathfrak{M}(z,\lambda,L).$ 

Theorem 5 Assume (H0)–(H2). Let c be the critical value. Then  $-c = \min_{\mu \in \mathfrak{C}(0)} \langle \mu, L \rangle.$ 

p.11

• Any minimizer  $\mu$  of the optimization problem

$$\min_{\mu\in\mathfrak{C}(0)}\langle\mu,L
angle.$$

is called a Mather measure.  $\mathfrak{M} = \mathfrak{M}(L)$ .

• We assume henceforth that c = 0. (Replace H by H - c if needed.)

The family  $(v^{\lambda})_{\lambda>0}$  is equi-Lipschitz and uniformly bounded on  $\mathbb{T}^n$  ( $\Rightarrow$  relatively compact in  $C(\mathbb{T}^n)$  by A<sup>2</sup> theorem).

(Uniform boundedness) Let  $v_0 \in C(\mathbb{T}^n)$  be a solution of (E). Let C > 0 be a constant such that  $||v_0||_{\infty} \leq C$ , and note that  $v_0 + C$  (reps.  $v_0 - C$ ) is a supersolution (resp. a subsolution) of  $(\mathsf{P}_{\lambda})$ .

By the comparison theorem, which is valid for  $(P_{\lambda})$  with  $\lambda > 0$ ,

$$v_0-C \leq v^\lambda \leq v_0+C \;\; orall \lambda > 0.$$

 $( \square ) \land ( \square ) : ( \square ) ( \square ) : ( \square )$ 

 $\mathcal{V}$  all accumulation points of  $(v^{\lambda})_{\lambda>0}$  in  $C(\mathbb{T}^n)$  as  $\lambda \to 0+$ . By the observation above,  $\mathcal{V} \neq \emptyset$ .

To show Theorem 3 (Davini et al.), it is enough to prove that  $\#(\mathcal{V}) \leq 1$ .

The main part of the proof (Theorem 3):

 $(\mathsf{Claim}\ 1) \qquad \quad \langle \mu, v \rangle \leq 0 \qquad \quad \forall v \in \mathcal{V}, \ \forall \mu \in \mathfrak{M}.$ 

(Claim 2) For  $\forall v, w \in \mathcal{V}, \, \forall z \in \mathbb{T}^n$ ,  $\exists \mu \in \mathfrak{M}$  s.t.

$$w(z) \leq v(z) + \langle \mu, w 
angle.$$

Claims 1 and 2 show that  $v, w \in \mathcal{V} \Rightarrow v = w$ . I.e.,  $\#\mathcal{V} \leq 1$ . Proof (sketch) of Claims 1 and 2

p.13

(日) (日) (日) (日) (日) (日) (日) (日)

Davini et al. have obtained two representations of the limit function of  $(v^{\lambda})$ . Here is one of them.

Theorem 6 Assume (H0)-(H2) and that c = 0. Let  $v^0 \in C(\mathbb{T}^n)$  be the limit function of  $(v^{\lambda})$ , that is,  $v^0 = \lim_{\lambda \to 0+} v^{\lambda}$  in  $C(\mathbb{T}^n)$ . Then  $v^0(x) = \max\{w(x) \mid w \in S, \ \langle \mu, w \rangle \leq 0 \ \forall \mu \in \mathfrak{M}\},$ where S denotes the set of all solutions of (E).

p.14

Remarks. • Davini et al. have proved Theorem 4 by using techniques from optimal control or dynamical systems (value functions, the Hopf-Lax-Oleinik formula). Mitake-Tran use the adjoint method introduced by L. C. Evans. Mitake-Tran-HI use the convex duality argument similar to those used by Gomes (Duality principles for fully nonlinear elliptic equations, 2005) and Mikami-Thieullen (Duality theorem for the stochastic optimal control problem, 2006). A feature of this approach by Mitake-Tran-HI is that it belongs to functional analysis and is easily adopted to different situations, for instance, 2nd-order elliptic equations, nonlocal equations, systems of PDEs without going into detailed studies of the underlying dynamics.

Siconolfi-HI use the convex duality in the form of the Hahn-Banach theorem.

p.15 ৰ অ > ৰঞ্জ > ৰছ > ৰছ - ৩৫৫ • The measures  $\mu \in \bigcup_{z,\lambda} \mathfrak{M}(z,\lambda,L)$  are supported in a common compact subset of  $\mathbb{T}^n \times \mathbb{R}^n$ . This is a consequence of the fact that  $\sup_{\lambda>0} \|Dv^{\lambda}\|_{\infty} < \infty$  (equi-Lipschitz). The set  $\bigcup_{z,\lambda} \mathfrak{M}(z,\lambda,L)$  is relatively compact in the topology of the weak convergence in the sense of measures.

p.16

#### Systems of HJ equations

Some recent results with Liang Jin.

The problem is now the m-system

$$\left\{egin{aligned} \lambda v_1^\lambda + H_1(x,Dv_1^\lambda,v^\lambda) &= 0 \quad ext{in } \mathbb{T}^n, \ &dots \ &dots\ \ &dots \ &dots \ &dots \ &dots \$$

We write for the system above simply

$$(\mathsf{P}_\lambda)$$
  $\lambda v^\lambda + H(x,Dv^\lambda,v^\lambda) = 0$  in  $\mathbb{T}^n,$   
where  $v^\lambda = (v_i^\lambda)$  and  $H = (H_i).$   
Assume

(1)  $H_i \in C(\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^m).$ (2)  $H_i$  is coercive, that is,

 $\lim_{|p| o\infty} H_i(x,p,u) = \infty$  uniformly for  $(x,u)\in \mathbb{T}^n imes B^m_R,\, orall R>0.$ 

· · · · · · · · · · · · · · · · P.17 oac

(3) 
$$(p, u) \mapsto H_i(x, p, u)$$
 is convex for any  $x \in \mathbb{T}^n$ .  
(4)  $H = (H_i)$  is monotone, that is, for  $u, v \in \mathbb{R}^m$ ,  
 $(u-v)_k = \max_i (u-v)_i \ge 0 \implies H_k(x, p, u) \ge H_k(x, p, v)$ .  
(5)  $H(x, Du, u) = 0$  has a solution  $u \in C(\mathbb{T}^n)^m$ .

Theorem 7 Assume (1)–(5) above. Then, as  $\lambda \to 0+$ , we have

$$v^{\lambda} 
ightarrow v^{0}$$
 in  $C(\mathbb{T}^{n})^{m}$ 

for some  $v^0 \in C(\mathbb{T}^n)^m$ .

Davini-Zavidovique (2019) have studied the case where the coupling is linear and the coupling coefficients are constants.

p.18

# Examples (coupling)

(E1) 
$$\begin{cases} \lambda u_1 + |Du_1| + u_1 - u_2 = f_1(x), \\ \lambda u_2 + |Du_2|^2 + u_2 - u_1 = f_2(x). \end{cases}$$

(E2) 
$$\begin{cases} \lambda u_1 + |Du_1| + (u_1 - u_2)^+ = f_1(x), \\ \lambda u_2 + |Du_2| + (u_2 - u_1)^+ = f_2(x). \end{cases}$$

(E3) 
$$\begin{cases} \lambda u_1 + |Du_1| + u_1 = f_1(x), \\ \lambda u_2 + |Du_2|^2 + u_2 = f_2(x). \end{cases}$$

		-1	2
n			u
μ	٠	-	
~	•	_	-

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへぐ

#### Some ideas for the proof.

• Set 
$$\mathbb{I} = \{1, \dots, m\}$$
 and  
 $L_i(x, \xi, \eta) = \sup_{(p,u)} [\xi \cdot p + \eta \cdot u - H_i(x, p, u)],$   
 $Y_i = \{\eta \in \mathbb{R}^m \mid \sum_{j \in \mathbb{I}} \eta_j \ge 0, \ \eta_j \le 0 \text{ for } j \neq i\}.$ 

Theorem 8 Assume (1)–(3). Then,
$$H$$
 monotone  $\iff L_i(x,\xi,\eta) = \infty$  for  $\eta \in \mathbb{R}^m \setminus Y_i$ 

-		0	n
ρ	•	2	υ

• When  $\lambda>0$ , we set  $T^{\lambda}(\eta)=1+\lambda^{-1}\sum_{j}\eta_{j}$  for  $\eta\in\mathbb{R}^{m}.$  Note that

$$T^{\lambda}(\eta) \geq 1 \ orall \eta \in Y_i, \ i \in \mathbb{I},$$
  
 $H^{\lambda}_{\phi+\lambda T^{\lambda_1}}(x, D(u+1), u+1) = H^{\lambda}_{\phi}(x, Du, u),$   
where  $\mathbf{1} = (1, \dots, 1) \in \mathbb{R}^m$  and  
 $H^{\lambda}_{\phi}(x, pu) = \left(\lambda u_i + \sup_{(\xi,\eta)} (\xi \cdot +\eta \cdot u - \phi_i(x, \xi, \eta))\right)_{i \in \mathbb{I}}$ .  
 $\mathcal{P}(\lambda)$  the set of collections  $\mu = (\mu_i)_{i \in \mathbb{I}}$  of  
nonnegative Borel measures  $\mu_i$  on  $\mathbb{T}^n \times \mathbb{R}^n \times Y_i$  such that  
 $\langle \mu_i, |\xi| + |\eta| \rangle < \infty \quad \forall i \in \mathbb{I}$  and  $\sum_{i \in \mathbb{I}} \langle \mu_i, T^{\lambda} \rangle = 1.$ 

 $\mathcal{P}(0)$  the set of collections  $\mu = (\mu_i)$  of nonnegative Borel measures  $\mu_i$  on  $\mathbb{T}^n \times \mathbb{R}^n \times Y_i$  such that

$$\langle \mu_i, |\xi|+|\eta|
angle <\infty$$
 and  $\sum_{i\in\mathbb{I}}\langle \mu_i,1
angle \leq 1.$ 

+ - + + + + + + + + + p.21 oq ()

• Fix  $(z, k, \lambda) \in \mathbb{T}^n \times I \times [0, \infty)$ .  $\mathfrak{C}(z, k, \lambda)$ , closed measures all  $\mu = (\mu_i) \in \mathcal{P}(\lambda)$  such that  $\lambda \psi_k(z) = \sum_{i \in \mathbb{I}} \langle \mu_i, \xi \cdot D\psi_i + \eta \cdot \psi + \lambda \psi_i \rangle \quad \forall \psi \in C^1(\mathbb{T}^n)^m$ .

Theorem 9 Assume (1)–(4). Then, if 
$$\lambda > 0$$
, $\lambda v_k^{\lambda}(z) = \min_{\mu \in \mathfrak{C}(z,k,\lambda)} \sum_{i \in I} \langle \mu_i, L_i \rangle.$ 

Discounted Mather measures  $\mathfrak{M}(z,k,\lambda)$ . Proof (sketch). We have  $\|(v^{\lambda}, Dv^{\lambda})\|_{\infty} < \infty$ , We may assume that for some R > 0,

$$egin{cases} L_i(x,\xi,\eta)=+\infty & ext{if} \ (\xi,\eta) 
ot\in K_i,\ L_i\in C(\mathbb{T}^n imes K_i), \end{cases}$$

where

$$K_i = \overline{B}_R^n imes (\overline{B}_R^m \cap Y_i), \ \ i \in \mathbb{I}.$$

$$egin{aligned} \mathcal{F}(\lambda) & ext{ all pairs } u = (u_i)_{i \in \mathbb{I}} \in C(\mathbb{T}^n)^m ext{ and } \ \phi &= (\phi_i)_{i \in \mathbb{I}} \in \prod_{i \in \mathbb{I}} C(\mathbb{T}^n imes K_i) ext{ such that } \ \lambda u(x) + H_\phi(x, Du(x), u(x)) \leq 0 & ext{ in } \mathbb{T}^n, \ ext{where } H_\phi &= (H_{\phi,i})_{i \in \mathbb{I}} ext{ and } \ H_{\phi,i}(x,p,v) &= \max_{(\xi,\eta) \in K_i} [p \cdot \xi + v \cdot \eta - \phi_i(x,\xi,\eta)]. \end{aligned}$$

Our claim now is: Theorem 9 holds when we replace  $\mathfrak{C}(z,k,\lambda)$  by

 $\mathfrak{C}_K(z,k,\lambda) := \{\mu = (\mu_i) \in \mathfrak{C}(z,k,\lambda) \mid \operatorname{supp} \mu_i \subset \mathbb{T}^n imes K_i\}.$ Similarly,  $\mathcal{P}_K(\lambda)$  for  $\lambda \geq 0$ .

p.23

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Set

$$\mathcal{G}(z,k,\lambda) = \{\phi - \lambda u_k(z)T^{\lambda}\mathbf{1} \mid (u,\phi) \in \mathcal{F}(\lambda)\},\$$
  
where  $\mathbf{1} = (1,\ldots,1) \in \mathbb{R}^m$ .  
This is a closed convex cone in  $\prod_{i \in \mathbb{I}} C(\mathbb{T}^n \times K_i)$  with vertex at the origin.

Theorem 10 Let 
$$(z, k, \lambda) \in \mathbb{T}^n \times \mathbb{I} \times (0, \infty)$$
 and  
 $\mu \in \mathcal{P}_K(\lambda)$ . Then,  $\mu \in \mathfrak{C}_K(z, k, \lambda)$  if and only if  
 $\sum_{i \in \mathbb{I}} \langle \mu_i, g_i \rangle \geq 0 \quad \forall g = (g_i) \in \mathcal{G}(z, k, \lambda).$ 

p.24

◆□ → < □ → < Ξ → < Ξ → < Ξ → < ○ < ○</p>

Proof (pictorial)  $(\exists 
u \in \mathfrak{M}(z,k,\lambda))$ 



p.25

=\_\_\_\_ 로 \_ 《로》《로》《唱》《日》

 $\prod_{i\in\mathbb{I}}C(\mathbb{T}^n imes K_i)$ 

## THANK YOU FOR YOUR ATTENTION!

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

# Appendix

<□ > < @ > < E > < E > E のQ @

Theorem 11 Let 
$$\chi$$
,  $u \in C(\mathbb{T}^n)$ . Let  
 $(z,\lambda) \in \mathbb{T}^n \times [0,\infty)$ . Assume (H0)–(H2) and that  $u$  is a  
subsolution of  $\lambda u + H(x,Du) = \chi$  in  $\mathbb{T}^n$ . Then  
 $\lambda u(z) \leq \langle \mu, L + \chi \rangle \quad \forall \mu \in \mathfrak{C}(z,\lambda).$ 

Proof (sketch). Assume that  $u \in C^1$ . Then

$$\lambda u(x) + \xi \cdot Du(x) \leq L(x,\xi) + \chi(x),$$

which implies

$$egin{aligned} \lambda u(z) &= \langle \mu, \lambda u + \xi \cdot D u 
angle \quad (\because \ \mu \in \mathfrak{C}(z,\lambda)) \ &\leq \langle \mu, L + \chi 
angle \ orall \mu \in \mathfrak{C}(z,\lambda). \end{aligned}$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Claim 1: Let  $v\in \mathcal{V}$  and  $\mu\in\mathfrak{M}.$  If we set  $\chi:=-\lambda v^\lambda$ , then $H(x,Dv^\lambda)=\chi$  in  $\mathbb{T}^n,$ 

and, by Theorem 11,

$$egin{aligned} 0 &\leq \langle \mu, L + \chi 
angle &= \langle \mu, L - \lambda v^\lambda 
angle \ &= \underbrace{\langle \mu, L 
angle}_{=0} - \langle \mu, \lambda v^\lambda 
angle = -\lambda \langle \mu, v^\lambda 
angle, \end{aligned}$$

and

$$\langle \mu, v^\lambda 
angle \leq 0.$$

In the limit as  $\lambda 
ightarrow 0+$ , we get Claim 1.

Claim 2: Fix any  $v, w \in \mathcal{V}$  and  $z \in \mathbb{T}^n$ . Choose a sequence  $\lambda_j \to 0+$  such that

$$v^{\lambda_j} o v$$
 in  $C(\mathbb{T}^n)$ .

By Theorem 4, we may choose a discounted Mather measure  $\mu_j \in \mathfrak{M}(z,\lambda_j).$  Observe that

$$\lambda_j w + H(x, Dw) = \lambda_j w,$$

and, by Theorem 11,

$$egin{aligned} \lambda_j w(z) &\leq \langle \mu_j, L + \lambda_j w 
angle &= \underbrace{\langle \mu_j, L 
angle}_{=\lambda_j v^{\lambda_j}(z)} + \lambda_j \langle \mu_j, w 
angle \ &= \lambda_j v^{\lambda_j}(z) + \lambda_j \langle \mu_j, w 
angle. \end{aligned}$$

Dividing the above by  $\lambda_j$  and taking the limit along a subsequence of  $(\lambda_j)$ , we get

$$w(z) \leq v(z) + \langle \mu, w 
angle$$

for some  $\mu\in\mathfrak{M}$  and, hence,  $w(z)\leq v(z).$ 

• Since 
$$(v^{\lambda}, L) \in \mathcal{F}(\lambda)$$
, we have  
 $L - \lambda v_{k}^{\lambda}(z)T^{\lambda}\mathbf{1} \in \mathcal{G}(z, k, \lambda)$  and, for all  $\mu \in \mathfrak{C}(z, k, \lambda)$ ,  
 $0 \leq \sum_{i \in \mathbb{I}} \langle \mu_{i}, L_{i} - \lambda v_{k}^{\lambda}(z)T^{\lambda} \rangle = -\lambda v_{k}^{\lambda}(z) + \sum_{i \in \mathbb{I}} \langle \mu_{i}, L_{i} \rangle.$ 

•  $\exists \nu \in \mathfrak{C}(z, k, \lambda)$  minimizer: Note that if  $\|\phi\|_{\infty} < 1$ , then  $(v^{\lambda}, L + \mathbf{1} + \phi) \in \mathcal{F}(\lambda)$ . This implies that  $\inf \mathcal{G}(z, k, \lambda) \neq \emptyset$ . We may show that  $L - \lambda v_k^{\lambda}(z)T^{\lambda}\mathbf{1} \in \partial \mathcal{G}(z, k, \lambda)$  By the Hahn-Banach theorem,  $\exists \nu \in \left(\prod_{i \in \mathbb{I}} C(K_i)\right)^*$  such that  $\nu \neq 0$  and

$$\langle 
u, L - \lambda v_k^\lambda(z) T^\lambda \mathbf{1} 
angle \leq \langle 
u, g 
angle \ \ \forall g \in \mathcal{G}(z,k,\lambda).$$

Since  $t(L-\lambda v_k^\lambda(z)T^\lambda\mathbf{1})\in \mathcal{G}(z,k,\lambda)$ , we see that

$$\langle 
u,L-\lambda v_k^\lambda(z)T^\lambda \mathbf{1}
angle=0.$$

• For  $\phi = (\phi_i)$ , if  $\phi_i \ge 0 \ \forall i \in \mathbb{I}$ , then  $(v^{\lambda}, L + \phi) \in \mathcal{F}(\lambda)$ . This, with the Riesz theorem, implies that  $\nu_i \ge 0$  and are Radon measures.